

$$1a) \vec{F}_1 + \vec{F}_2 + \vec{F}_3 + \vec{F}_4 = 0$$

$$\Rightarrow \begin{cases} F_{1x} + F_{2x} + F_{3x} + F_{4x} = 0 \\ F_{1y} + F_{2y} + F_{3y} + F_{4y} = 0 \end{cases}$$

$$\Rightarrow \begin{cases} F_1 \cos \theta_1 - F_2 \sin \theta_2 - F_3 \cos \theta_3 + F_{4x} = 0 \\ -F_1 \sin \theta_1 - F_2 \cos \theta_2 + F_3 \sin \theta_3 + F_{4y} = 0 \end{cases}$$

$$\Rightarrow \begin{cases} F_{4x} = -F_1 \cos \theta_1 + F_2 \sin \theta_2 + F_3 \cos \theta_3 \\ F_{4y} = +F_1 \sin \theta_1 + F_2 \cos \theta_2 - F_3 \sin \theta_3 \end{cases}$$

$$F_4 = \sqrt{F_{4x}^2 + F_{4y}^2} = \dots$$

$$\tan \theta_4 = \frac{F_{4y}}{F_{4x}}$$

1A

sec 801-803

$$1b) y(t) = c_1 t^4 + c_2 t^3 + k_1 t + k_2$$

$$y(t=0) = H$$

$$v(t=0) = W$$

$$y(t=0) = k_2 = H \Rightarrow \boxed{k_2 = H}$$

$$v(t) = \frac{d}{dt} y(t) = 4c_1 t^3 + 3c_2 t^2 + k_1$$

$$v(t=0) = k_1 = W \Rightarrow \boxed{k_1 = W}$$

$$a(t) = \frac{d}{dt} v(t)$$

$$a(t) = 12c_1 t^2 + 6c_2 t$$

$$2) \begin{aligned} a_x(t) &= \alpha t^2 & x(t=0) &= 0 \\ a_y(t) &= -\beta t & y(t=0) &= 0 \end{aligned}$$

maximum? $v_y(t=T) = 0$ $v_m \sin \theta$

$$v_y(t) = \int a_y(t) dt + v_{oy} = -\frac{1}{2}\beta t^2 + v_{oy}$$

$$v_y(t=T) = 0 \Rightarrow -\frac{1}{2}\beta T^2 + v_{oy} = 0$$

$$\Rightarrow T = \sqrt{\frac{2v_{oy}}{\beta}}$$

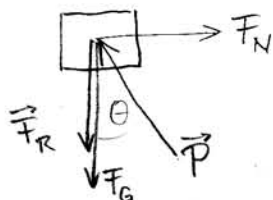
$$v_x(t) = \int a_x(t) dt + v_{ox} = \frac{1}{3}\alpha t^3 + v_{ox}$$

$$x(t) = \int v_x(t) dt + x_0 = \frac{1}{12}\alpha t^4 + v_{ox} \cdot t + 0$$

$$x(t=T) = \frac{\alpha}{12} \frac{4v_m^2 \sin^2 \theta}{\beta^2} + v_m \cos \theta \sqrt{\frac{2v_m \sin \theta}{\beta}}$$

1A

3a) ① FBD ② Newton ③ Solve equations 1A



sec 801-803

$$\textcircled{2} F_x = ma_x = 0 \quad (!) \quad F_y = ma_y \quad +9.8 \frac{m}{s^2}$$

$$P_x + F_{Nx} + F_{Gx} + F_{Rx} = 0 \quad P_y + F_{Ny} + F_{Gy} + F_{Ry} = ma_y$$

$$-P \sin \theta + F_N + 0 + 0 = 0 \quad P \cos \theta + 0 - mg - \mu F_N = ma_y$$

$$\Rightarrow F_N = P \sin \theta = -P_x$$

$$\Rightarrow ma_y = P \cos \theta - mg - \mu P \sin \theta$$

$$\Rightarrow a_y = -g + \frac{P}{m} (\cos \theta - \mu \sin \theta)$$

$$v(t) = a_y \cdot t$$

3b) $\vec{P} = \frac{P_x}{-c_1} \vec{x} + \overbrace{(mg + \alpha t)}^{P_y} \vec{y}$ 1A

$$ma_y^* = P \cos \theta - mg - \mu P \sin \theta =$$

$$= P_y - mg + \mu P_x =$$

$$= (mg + \alpha t) - mg + \mu (-c_1) =$$

$$= \alpha t - \mu c_1$$

Attention! $a(t) \geq 0$ for all times

$$\Rightarrow a(t) = \begin{cases} 0 & \text{for } t \leq T \\ \alpha^*(t) & \text{for } t > T \end{cases}$$

calc. T : $\alpha T - \mu c_1 = 0 \Rightarrow T = \frac{\mu c_1}{\alpha}$

$$\Rightarrow v(t) = 0 \quad \text{for } t \leq T$$

$$v(t) = \int a dt + c_0 = \frac{\alpha}{2} t^2 - \mu c_1 t + c_0$$

$$v(t=T) = 0 = \frac{\alpha}{2} \frac{\mu^2 c_1^2}{\alpha^2} - \frac{\mu^2 c_1^2}{\alpha} + c_0 = -\frac{\mu^2 c_1^2}{2\alpha} + c_0$$

$$\Rightarrow c_0 = \frac{\mu^2 c_1^2}{2\alpha}$$

1a) $\vec{F}_1 + \vec{F}_2 + \vec{F}_3 + \vec{F}_4 = 0$ 1B
 $\Rightarrow \begin{cases} F_{1x} + F_{2x} + F_{3x} + F_{4x} = 0 \\ F_{1y} + F_{2y} + F_{3y} + F_{4y} = 0 \end{cases}$ sec 810-812

$$\Rightarrow \begin{cases} -F_1 \sin \theta_1 - F_2 \sin \theta_2 + F_3 \cos \theta_3 + F_{4x} = 0 \\ +F_1 \cos \theta_1 - F_2 \cos \theta_2 - F_3 \sin \theta_3 + F_{4y} = 0 \end{cases}$$

$$F_1 = m_1 g, \quad F_2 = m_2 g, \quad F_3 = m_3 g$$

$$\Rightarrow \begin{cases} +m_1 g \sin \theta_1 - m_2 g \sin \theta_2 + m_3 g \cos \theta_3 + F_{4x} = 0 \\ +m_1 g \cos \theta_1 - m_2 g \cos \theta_2 - m_3 g \sin \theta_3 + F_{4y} = 0 \end{cases}$$

$$\Rightarrow \begin{cases} F_{4x} = +m_1 g \sin \theta_1 + m_2 g \sin \theta_2 - m_3 g \cos \theta_3 \\ F_{4y} = -m_1 g \cos \theta_1 + m_2 g \cos \theta_2 + m_3 g \sin \theta_3 \end{cases}$$

$$F_4 = \sqrt{F_{4x}^2 + F_{4y}^2} = \dots ; \quad F_4 = m_4 g = \dots$$

$$\tan \theta_4 = \frac{F_{4y}}{F_{4x}} = \dots$$

1b) $x(t) = c_1 t^4 + c_2 t^3 + k_1 t + k_2$ 1B
 $x(t=0) = L$ \uparrow
=? \uparrow
=?
 $v(t=0) = w$

$$x(t=0) = k_2 = L \Rightarrow \boxed{k_2 = L}$$

$$v(t) = \frac{d}{dt} x(t) = 4c_1 t^3 + 3c_2 t^2 + k_1$$

$$v(t=0) = k_1 \Rightarrow \boxed{k_1 = w}$$

$$\boxed{a(t) = \frac{d}{dt} v(t) = 12c_1 t^2 + 6c_2 t}$$

2) $x(t=T) = C$ $v_{0x} = v_0 \cos \theta$ 1B
 $y(t=T) = D$ $v_{0y} = v_0 \sin \theta$

$$\begin{aligned} x(t=0) &= 0 & a_x &= 0 & v_0 &=? \\ y(t=0) &= A & a_y &= -\beta t & (T &=?) \end{aligned}$$

$$x(t) = v_{0x} \cdot t \quad \text{because } a_x = 0 \text{ \& } x(0) = 0$$

$$x(t=T) = C \Rightarrow v_{0x} \cdot T = C \Rightarrow \boxed{T = \frac{C}{v_{0x}}}$$

$$v_y(t) = \int (-\beta t) dt + v_{0y} = -\frac{1}{2} \beta t^2 + v_{0y}$$

$$y(t) = \int \left(-\frac{1}{2} \beta t^2 + v_{0y}\right) dt + y_0 = -\frac{1}{6} \beta t^3 + v_{0y} t + A$$

$$y(t=T) = D = -\frac{1}{6} \beta \frac{C^3}{v_0^3 \cos^3 \theta} + \frac{v_0 \sin \theta}{v_0 \cos \theta} \cdot C + A = D$$

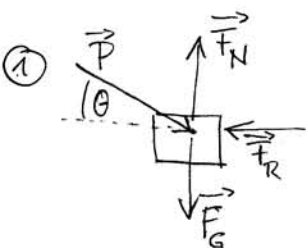
$$\Rightarrow \frac{\beta}{6} \frac{C^3}{v_0^3 \cos^3 \theta} = D - A - C \cdot \tan \theta$$

$$\Rightarrow v_0^3 = \frac{\beta C^3}{6 \cos^3 \theta} \frac{1}{D - A - C \tan \theta}$$

$$\Rightarrow v_0 = \frac{C}{\cos \theta} \sqrt[3]{\frac{\beta}{6(D - A - C \tan \theta)}}$$

3a)

- ① FBD ② Newton ③ Solve equations



sec 810-812

② $F_x = ma_x$ $F_y = ma_y = 0 (!)$

$$P_x + F_{Nx} + F_{Gx} + F_{Rx} = ma_x \quad P_y + F_{Ny} + F_{Gy} + F_{Ry} = 0$$

$$+ P \cos \theta + 0 + 0 - \mu F_N = ma_x \quad -P \sin \theta + F_N - mg + 0 = 0$$

③ $P \cos \theta - \mu(P \sin \theta + mg) = ma_x$ $\Rightarrow F_N = P \sin \theta + mg$

$$\Rightarrow a_x = \frac{P}{m} (\cos \theta - \mu \sin \theta) - \mu g$$

$$\Rightarrow v(t) = \left[\frac{P}{m} (\cos \theta - \mu \sin \theta) - \mu g \right] \cdot t$$

because $a(t) = a(x)$ and $v(t=0) = 0$

3b)

1B

$$a = \frac{P}{m} (\cos \theta - \mu \sin \theta) - \mu g$$

$$\theta = 0 \quad P = \alpha t$$

$$\Rightarrow a^*(t) = \frac{\alpha t}{m} - \mu g$$

Attention! $a(t) \geq 0$ for all times

$$\Rightarrow a(t) = 0 \quad \text{for } t \leq T$$

$$a(t) = a^*(t) \quad \text{for } t > T$$

calc. T : $\frac{\alpha T}{m} - \mu g = 0 \Rightarrow T = \frac{m \mu g}{\alpha}$

$$\Rightarrow v(t) = 0 \quad \text{for } t \leq T$$

$$v(t) = \int a dt + c = \frac{\alpha t^2}{2m} - \mu g t + c$$

$$v(t=T) = 0 = \frac{\alpha m^2 \mu g^2}{2m \alpha} - \frac{m}{\alpha} \mu g^2 + c \Rightarrow c = \dots$$